

POS-tagging and Hidden Markov Models unit:

- ▶ The POS-tagging problem (Monday)
- ▶ HMM definition and problem statements (Wednesday)
- ▶ Solution to Problem 1 (forward algorithm) and POS application (Wednesday and Friday)
- ▶ Solution to Problem 2 (Viterbi algorithm) and POS application (Friday and next week Monday)
- ▶ Solution to Problem 3 (EM/Baum-Welch algorithm) and linguistic application (next week Monday and Wednesday)

Universal		Penn Treebank		
ADJ	Adjective	JJ	Adjective	<i>yellow</i>
		JJR	Comparative adjective	<i>bigger</i>
		JJS	Superlative adjective	<i>wildest</i>
ADP	Adposition	IN	Preposition	<i>of, in , by</i>
		RP	Particle	<i>up, off</i>
ADV	Adverb	RB	Adverb	<i>quickly</i>
		RBR	Comparative adverb	<i>faster</i>
		RBS	Superlative adverb	<i>fastest</i>
		WRB	Wh-adverb	<i>how, where</i>
CONJ	Conjunction	CC	Coordinating conjunction	<i>and, but, or</i>

	Universal		Penn Treebank	
DET	Determiner, article	DT	Determiner	<i>a, the</i>
		PDT	Predeterminer	<i>all, both</i>
		PRP\$	Possessive pronoun	<i>your, one's</i>
		WDT	Wh-determiner	<i>which, that</i>
		WP\$	Wh-possessive	<i>whose</i>
NOUN	Noun	NN	Singular or mass noun	<i>llama</i>
		NNP	Proper noun, singular	<i>IBM</i>
		NNPS	Noun, plural	<i>llamas</i>
NUM	Numeral	CD	Cardinal number	<i>one, two</i>
PRT	Particle	POS	Possessive ending	<i>'s</i>
		TO	"to" [Infinitive marker]	<i>to</i>
PRON	Pronoun	EX	Existential "there"	<i>there</i>
		PRP	Personal pronoun	<i>I, you, he</i>
		WP	Wh-pronoun	<i>what, who</i>

Universal		Penn Treebank		
VERB	Verb	MD	Modal <i>can, should</i>	
		VB	Verb base	<i>eat</i>
		VBD	Verb past tense	<i>ate</i>
		VBG	Verb gerund	<i>eating</i>
		VBN	Verb past participle	<i>eaten</i>
		VBP	Verb non-3sp	<i>eat</i>
		VBZ	Verb 3sp	<i>eats</i>
<hr/>				
.	Punctuation mark	(none)		
<hr/>				
X	Other	FW	Foreign word	<i>mea culpa</i>
		LS	List item marker	<i>1, 2, One</i>
		SYM	Symbol	<i>+, %, &</i>
		UH	Interjection	<i>ah, oops</i>

PRON	VERB	PRT	VERB	ADP	DET	ADJ	NOUN
I	rose	to	saw	off	the	still	rose

PRON	PRON	VERB	ADV	VERB	ADP	DET	NOUN
that	I	saw	still	grew	by	the	still.

Suppose we want to determine the average annual temperature at a particular location on earth over a series of years.

To simplify the problem, we consider only two annual temperatures, “hot” and “cold.” Suppose that evidence indicates that the probability of a hot year followed by another hot year is 0.7 and the probability that a cold year is followed by another cold year is 0.6.

Also suppose that research indicates a correlation between the size of tree growth rings and temperature. For simplicity, we consider only three different tree ring sizes: small, medium, and large. Finally suppose hot years are more likely to result in large tree rings, cold years in small.

	<i>H</i>	<i>C</i>	<i>S</i>	<i>M</i>	<i>L</i>
<i>H</i>	0.7	0.3	0.1	0.4	0.5
<i>C</i>	0.4	0.6	0.7	0.2	0.1

Mark Stamp, “A Revealing Introduction to Hidden Markov Models”. Abridged.

Let Q be a set of N states types. Use $i, j, ii, jj \in [0, N)$ to index into Q .

Let V be a set of M symbols types. Use $k \in$ to index into V .

Let \bar{S} be a sequence of T state tokens and \bar{O} be a sequence of T observation tokens.
Use $t \in [0, T)$ to index into \bar{O} and \bar{S}

Thus $\bar{O} = \langle \mathcal{O}_0, \mathcal{O}_1, \dots, \mathcal{O}_{T-1} \rangle$ is a sequence of observation tokens, e.g., $\mathcal{O}_t = v_k$,
and $\bar{S} = \langle S_0, S_1, \dots, S_{T-1} \rangle$ is a sequence of state tokens, e.g., $S_t = q_j$.

A **hidden Markov model** is a triple $\lambda = (A, B, \pi)$ where

- ▶ A is an $N \times N$ matrix of state transition probabilities: $a_{ij} = P(S_{t+1} = q_j \mid S_t = q_i)$
- ▶ B is an $N \times M$ matrix of emission (or observation) probabilities:
 $b_j(k) = P(\mathcal{O}_t = v_k \mid S_t = q_j)$
- ▶ π is the initial state distribution. $\pi_i = P(S_0 = q_i)$

Four HMM problems:

- Problem 0.** Given \bar{O} together with \bar{S} , compute $\lambda = (A, B, \pi)$ most likely to have produced those sequences.
[Solution: MLE, possibly with smoothing.]
- Problem 1.** Given $\lambda = (A, B, \pi)$ and \bar{O} , compute the probability that λ assigns to \bar{O} .
[Solution: The forward algorithm.]
- Problem 2.** Given $\lambda = (A, B, \pi)$ and \bar{O} , find \bar{S} that maximizes the probability that λ assigns to \bar{O} .
[Solution: The Viterbi algorithm.]
- Problem 3.** Given \bar{O} , M (or V), and N , find $\lambda = (A, B, \pi)$ that maximizes the likelihood of \bar{O} .
[Solution: The Baum-Welch algorithm, a version of EM.]

$$\alpha_t(i) = P(\bar{\mathcal{O}}[: t + 1], S_t = q_i | \lambda) = \begin{cases} \pi_i \cdot b_i(\mathcal{O}_0) & \text{if } t = 0 \\ \left(\sum_{j=0}^{N-1} \alpha_{t-1}(j) \cdot a_{ji} \right) \cdot b_i(\mathcal{O}_t) & \text{otherwise} \end{cases}$$

$$\beta_t(i) = P(\bar{\mathcal{O}}[t+1:] | S_t = q_i) = \begin{cases} 1 & \text{if } t = T - 1 \\ \sum_{j=0}^{N-1} a_{ij} \cdot b_j(\mathcal{O}_{t+1}) \cdot \beta_{t+1}(j) & \text{if } t < T - 1 \end{cases}$$

$$\delta_t(i) = \max_{\bar{S}[t:t+1]} P(\bar{O}[t:t+1], \bar{S}[t:t+1] \mid S_t = q_i)$$

$$= \begin{cases} \pi_i \cdot b_i(\mathcal{O}_0) & \text{if } t = 0 \\ \left(\max_{0 \leq j < N} \delta_{t-1}(j) \cdot a_{ji} \right) \cdot b_i(\mathcal{O}_t) & \text{otherwise} \end{cases}$$

$$\psi_t(i) = \operatorname{argmax}_{q_j} P(S_{t-1} = q_j, S_t = q_i \mid \bar{O}[: t + 1])$$

$$= \begin{cases} \text{None} & \text{if } t = 0 \\ \operatorname{argmax}_{0 \leq j < N} \delta_{t-1}(j) \cdot a_{ji} & \text{if } t > 0 \end{cases}$$

$$\begin{aligned}\lg \sum_{i=0}^{n-1} x_i &= \lg(x_0 + x_1 + \cdots + x_{n-1}) \\ &= \lg x_0 + \lg \left(1 + \sum_{i=1}^{n-1} \frac{x_i}{x_0} \right) \\ &= \lg x_0 + \lg \left(1 + \sum_{i=1}^{n-1} 2^{\lg x_i - \lg x_0} \right)\end{aligned}$$

$$\begin{aligned}
\xi_t(i, j) &= P(S_t = q_i, S_{t+1} = q_j \mid \bar{\mathcal{O}}, \lambda) \\
&= \frac{P(S_t = q_i, S_{t+1} = q_j, \bar{\mathcal{O}} \mid \lambda)}{P(\bar{\mathcal{O}} \mid \lambda)} \\
&= \frac{\alpha_t(i) \cdot a_{ij} \cdot b_j(\mathcal{O}_{t+1}) \cdot \beta_{t+1}(j)}{\sum_{i\bar{i}} \sum_{j\bar{j}} \alpha_t(i\bar{i}) \cdot a_{i\bar{i} j\bar{j}} \cdot b_{j\bar{j}}(\mathcal{O}_{t+1}) \cdot \beta_{t+1}(j\bar{j})}
\end{aligned}$$

$$\gamma_t(i) = P(S_t = q_i \mid \bar{O}, \lambda)$$

$$= \sum_{j=0}^{N-1} P(S_t = q_i, S_{t+1} = q_j \mid \bar{O}, \lambda)$$

$$= \sum_{j=0}^{N-1} \xi_t(i, j)$$

$$\pi_i = \gamma_0(i)$$

$$a_{ij} = \frac{\text{expected transitions from } q_i \text{ to } q_j}{\text{expected transitions from } q_i} = \frac{\sum_{t=0}^{T-2} \xi_t(i, j)}{\sum_{t=0}^{T-2} \gamma_t(i)}$$

$$b_i(k) = \frac{\text{expected times } q_i \text{ emits } v_k}{\text{expected times in } q_i} = \frac{\sum_{t=0}^{T-2} \{\gamma_t(i) \mid \mathcal{O}_t = v_k\}}{\sum_{t=0}^{T-2} \gamma_t(i)}$$

Coming up:

- ▶ Language model programming assignment (Mon, Sept 25)
- ▶ POS quiz (Thurs, Sept 21)
- ▶ Reading from J&M, Sections 8.(0–4) (Fri, Sept 22)
- ▶ HMM quiz (Tues, Sept 26)
- ▶ HMM programming assignment (Wed, Oct 4)