

Bellman-Ford Algorithm (SSSP)

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Initialize all vertices to have infinite bound and no parent \begin{aligned} \operatorname{distances}[s] &= 0 \\ \operatorname{Repeat} &|V| - 1 \text{ times} \\ \operatorname{For each} &u \in V \\ \operatorname{For each} &v \in \operatorname{adjacents}(u) \\ \operatorname{If distances}[v] &> \operatorname{distances}[u] + w(u,v) \\ \operatorname{distances}[v] &= \operatorname{distances}[u] + w(u,v) \\ \operatorname{parents}[v] &= u \end{aligned}
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Dijkstra's Algorithm (SSSP)

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Initialize all vertices to have infinite bound and no parent \mathtt{distances}[s] = 0
Make a priority queue pq with all vertices
While pq is not empty
u = pq.\mathtt{extractMax}()
For each v \in \mathtt{adjacents}(u)
\mathtt{If \ distances}[v] > \mathtt{distances}[u] + w(u,v)
\mathtt{distances}[v] = \mathtt{distances}[u] + w(u,v)
\mathtt{parents}[v] = u
pq.\mathtt{increaseKey}(v)
```

